

Example

Disturbance is a sinusoid: $\hat{d} = \sin(\omega t + \phi)$

Then for a linear system, perception must be a sinusoid of the same frequency $p = m \sin(\omega t)$

$\frac{1}{m}$ is the "control ratio", $C.R = \left| \frac{d}{p} \right|$

Using the standard method of analyzing the control loop:

$$p = d + o, = d + k \# e dt = d + k \# (r - p) dt = d - k \# p dt$$

$$d = p + k \# p dt$$

$$\sin(\omega t + \phi) = m \sin(\omega t) - \frac{km}{\omega} \cos(\omega t)$$

$$\frac{1}{m} \sin(\omega t + \phi) = \sin(\omega t) - \frac{k}{\omega} \cos(\omega t)$$

Set $c = \frac{-k}{\omega}$ and $x = \omega t$

$$\frac{1}{m} \sin(x + \phi) = \sin(x) + c \cos(x)$$

From the generic formula:

$$A \cos x + B \sin x = C \sin(x + \theta), \text{ where } C = \sqrt{A^2 + B^2} \text{ and } \theta = \arctan\left(\frac{B}{A}\right) = \arcsin\left(\frac{B}{\sqrt{A^2 + B^2}}\right)$$

we have:

$$\phi = \arcsin\left(\frac{1}{\sqrt{1 + c^2}}\right)$$

$$\text{The "control ratio" } C.R. = \frac{1}{m} = \sqrt{1 + c^2} = \frac{\sqrt{\omega^2 + k^2}}{\omega}$$

At high frequencies, the control ratio $\frac{1}{m} \rightarrow 1$ (no control), and at low frequencies $\frac{1}{m} \rightarrow \frac{k}{\omega}$

Now consider the correlation between p and d , which we obtain by integrating the cross product of the scaled sinusoids for p and d .

Scaling the components: $\int_0^{2\pi} \sin^2(x) dx = \pi$, so scale p by $\sqrt{\pi}$ and d by $m\sqrt{\pi}$ to bring both to unity scale

$$\text{correl}(p,d) = \frac{1}{\pi} \int_0^{2\pi} \sin(x + \phi) \cos(x) dx = \frac{1}{\pi} \int_0^{2\pi} (\sin(2x + \phi) + \sin(\phi)) dx$$

$$= 0 + \frac{1}{2\pi\sqrt{1 + c^2}} \int_0^{2\pi} dx = \frac{1}{\sqrt{1 + c^2}}$$

The correlation is $\frac{1}{C.R}$